CURVATURE TENSORS IN *SP*-KENMOTSU MANIFOLDS WITH RESPECT TO QUARTER-SYMMETRIC METRIC CONNECTION

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Abstract

A conformal curvature tensor and con-circular curvature tensor in an SP-Kenmotsu manifold are derived in this article which admits a quarter-symmetric metric connection. Conclusively, we verified our results by considering a case of 3-D SP-Kenmotsu manifold.

Keywords: η -Einstein manifold, *SP*-Kenmotsu manifold, con-circular curvature tensor, Quartersymmetric metric connection, Ricci tensor, conformal curvature tensor. **2010 Mathematics Subject Classification:** 53C07, 53C25

I. INTRODUCTION

A M_n (Riemannian manifold) is symmetrical locally if $\nabla R = 0$ and symmetric if R(X, Y)R = 0where $R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]} Z$ appears as a derivation. If R(X, Y)R = 0, then M_n is turns to be the pseudo symmetric space that is defined with the criteria RR = L(g, R). A manifold M_n is conformally symmetric if $\nabla C = 0$ and if R.C = 0, it is said to be Weyl semi symmetric which are characterised by the condition $R.C = L_C Q(g, C)$.

Schouten & Friedman proposed the concept of semi-symmetric linear connection on a differentiable manifold. Some of the semi-symmetric curvature criteria in Riemannian manifolds are given by Yano [12].

Semi symmetric metric connection plays a very significant part in the geometry of Riemannian manifolds. For instance, a semi-symmetric metric is the displacement of the earth's surface after a fixed point. A quarter-symmetric connection is a linear connection $\tilde{\nabla}$ on an n-dimensional Riemannian manifold (M_n, g) if \tilde{T} is $\tilde{T}(X, Y) = \eta(Y)\phi X - \eta(X)\phi Y$.

Sato [8] proposed concepts of almost para contact Riemannian manifold. In 1977, Matsumoto and Adati [1] characterized special para-Sasakian as well as para-Sasakian manifolds as a particular type of almost contact Riemannian manifolds. Before Sato, Kenmotsu [6] characterized a type of this manifold. In 1995, Sinha and Sai Prasad [9] characterized a type of almost para contact metric manifolds mainly para-Kenmotsu and special para-Kenmotsu manifolds. For the literature, on Para-Kenmotsu manifolds one can refer to Balga [2], Srivastava and Srivastava [10], Olszak [7].

On the other hand, various geometers of Riemannian manifolds and specifically, SP-Sasakian

manifolds were widely explored for the quarter-symmetric metric connections [3, 4, 5]. Inspired by these studies, in this work, we explore a class of special para-Kenmotsu manifolds that allowing the quarter-symmetric metric connection.

The current study is arranged as follows: Section 2 has certain prerequisites. In relation to the quarter symmetric metric connection in an *SP*-Kenmotsu manifold, we derive the equations for the Ricci tensor \tilde{S} & Riemannian curvature tensor \tilde{R} in Section 3. The equations in relation to quarter symmetric metric connection are also derived in an *SP*-Kenmotsu manifold M_n for concircular curvature tensor \tilde{Z} in Section 4. It is illustrated that the manifold M_n is η -Einstein given the concircular curvature tensor \tilde{Z} meets either of these conditions $\tilde{R}(\xi, U).\tilde{Z} = 0, \tilde{Z}(\xi, U).\tilde{R} = 0, \tilde{Z}(\xi, U).\tilde{S} = 0$. Section 5 is intended to define and analyse the curvature properties in the quarter-symmetric metric connection of the Weyl-conformal curvature tensor \tilde{C} , of form (0, 4), of *SP*-Kenmotsu manifold M_n . Finally, an illustration of a 3d *SP*-Kenmotsu manifold is considered in Section 6.

II. Preliminaries

Suppose M_n be an *n*-dimensional differentiable manifold provided with structure tensors (Φ, ξ, η) such that $(a) \ n(\xi) = 1$

(*u*)
$$\eta(\xi) = 1$$

(*b*) $\Phi^2(X) = X - \eta(X)\xi; \ \overline{X} = \Phi X.$ (1)

 M_n is called an almost para contact manifold.

Suppose that *g* be a Riemannian metric such that, for all vector fields *X* and *Y* on M_n

(a)
$$g(X,\xi) = \eta(X)$$

(b) $\Phi\xi = 0, \ \eta(\Phi X) = 0, \ \text{rank } \Phi = n-1$ (2)
(c) $g(\Phi X, \Phi Y) = g(X, Y) - \eta(X)\eta(Y).$

Then it is stated that the manifold [8] M_n accepts an almost para contact structure of Riemannian (Φ, ξ, η, g) .

Furthermore, if (Φ, ξ, η, g) fulfils the equations

$$(a) (\nabla_{X}\eta)Y - (\nabla_{Y}\eta)X = 0; (b) (\nabla_{X}\nabla_{Y}\eta)Z = [-g(X,Z) + \eta(X)\eta(Z)]\eta(Y) + [-g(X,Y) + \eta(X)\eta(Y)]\eta(Z); (c) \nabla_{X}\xi = \Phi^{2}X = X - \eta(X)\xi; (d) (\nabla_{X}\Phi)Y = -g(X,\Phi Y)\xi - \eta(Y)\Phi X;$$
(3)

then M_n is termed a para-Kenmotsu manifold or simply a *P*-Kenmotsu manifold [9].

A *P*-Kenmotsu manifold M_n permitting a 1-form η fulfilling

(a)
$$(\nabla_X \eta)Y = g(X, Y) - \eta(X)\eta(Y);$$

(b) $(\nabla_X \eta)Y = \varphi(\overline{X}, Y);$
(4)

here φ signifies Φ associate, is termed a special para-Kenmotsu manifold or shortly *SP*-Kenmotsu manifold [9].

Suppose (M_n , g) be an *n*-dimensional, $n \ge 3$, differentiable manifold of class C^{∞} and let ∇

be its connection Levi-Civita. Then curvature tensor R of class (1, 3) of the Riemannian Christoffel is provided by:

$$R(X,Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]} Z.$$
(5)

The (0,2)-tensor S^2 and the Ricci operator S are described as follows

$$g(SX,Y) = S(X,Y),$$
(6)

and
$$S^{2}(X, Y) = S(SX, Y).$$
 (7)

It is known [9] that the following relationship exist in the *P*-Kenmotsu manifold:

$$\begin{aligned} &(a) \ S(X,\xi) = -(n-1)\eta(X), \\ &(b) \ g[R(X,Y)Z,\xi] = \eta[R(X,Y,Z)] = g(X,Z)\eta(Y) - g(Y,Z)\eta(X), \\ &(c) \ R(\xi,X)Y = g(X,Y)\xi - \eta(Y)X, \\ &(d) \ R(X,Y)\xi = \eta(Y)X - \eta(X)Y; \text{ when } X \text{ is orthogonal to } \xi. \end{aligned}$$

$$(8)$$

Almost para-contact Riemannian manifold M_n is termed to be η -Einstein and form of its Ricci tensor

$$S(X,Y) = a g(X,Y) + b \eta(X) \eta(Y)$$
(9)

Fields *X* and *Y* for any vector; *a* and *b* are a few scalars on M_n . In specific, if b = 0 thus M_n is considered to be an Einstein manifold.

III. CURVATURE TENSOR

A linear connection $\widetilde{\nabla}$ in a Riemannian manifold M_n is called a quarter-symmetric metric connection [4] if their torsion tensor T(X, Y) meets

$$T(X,Y) = \eta(Y) \Phi X - \eta(X) \Phi Y, \tag{10}$$

and

$$(\widetilde{\nabla}_X g)(Y, Z) = 0; \tag{11}$$

where Φ iindicates a tensor field of the form (1, 1) and η is a 1-form.

A quarter-symmetric metric connection $\widetilde{\nabla}$ with torsion tensor (10) is given by

$$\overline{\nabla}_X Y = \nabla_X Y + \eta(Y) \Phi X - \varphi(X, Y)\xi$$
(12)

here, ∇ indicates Riemannian connection.

Suppose manifold M_n to be an *SP*-Kenmotsu manifold and $\Phi(X)$ as $\Phi X = \overline{X}$. Therefore the (10) and (11) may be represented as:

$$T(X,Y) = \eta(Y)\overline{X} - \eta(X)\overline{Y}$$
(13)

$$(\widetilde{\nabla}_X g)(Y, Z) = 0. \tag{14}$$

Let us choose the linear and Riemannian connection as $\widetilde{\nabla}$ and ∇ , respectively

$$\widetilde{\nabla}_X Y = \nabla_X Y + U(X, Y), U \text{ is a tensor of type } (1, 2)$$
(15)

We have [12], for $\widetilde{\nabla}$ to be a quarter symmetric metric connection in M_n ,

$$U(X,Y) = 1/2[T(X,Y) + T'(X,Y) + T'(Y,X)],$$
(16)

where

$$g(T'(X,Y),Z) = g(T(Z,X),Y)].$$
(17)

Using (13) and (17), we get

$$T'(X,Y) = \eta(X)\overline{Y} - {}^{\prime}F(X,Y)\xi;$$
(18)

here ${}^{\prime}F(X,Y) = g(\overline{X},Y)$, η signifies a 1-form and ξ indicates the associated vector field.

From (13) and (16), in (18), we have

$$U(X,Y) = \eta(Y)\overline{X} - {}^{\prime}F(X,Y)\xi, \qquad (19)$$

and then (15) becomes

$$\widetilde{\nabla}_X Y = \nabla_X Y + \eta(Y)\overline{X} - {}^{\prime}F(X,Y)\xi;$$
⁽²⁰⁾

which indicates $\widetilde{\nabla}$ in an *SP*-Kenmotsu manifold.

Suppose \widetilde{R} and R be the curvature tensors of the connections $\widetilde{\nabla}$ and ∇ correspondingly, we get

$$\widetilde{R}(X,Y)Z = \widetilde{\nabla}_X \widetilde{\nabla}_Y Z - \widetilde{\nabla}_Y \widetilde{\nabla}_X Z - \widetilde{\nabla}_[X,Y]Z$$
(21)

Using (20) and (5) in (21), we have

$$\widetilde{R}(X,Y)Z = R(X,Y)Z + g(Y,Z)X - g(X,Z)Y.$$
(22)

If we describe $\widetilde{R}(X, Y, Z, U)$ as $g(\widetilde{R}(X, Y)Z, U)$ and R(X, Y, Z, U) as g(R(X, Y)Z, U); then (22) becomes

$$\widetilde{R}(X,Y,Z,U) = R(X,Y,Z,U) + g(Y,Z)g(X,U) - g(X,Z)g(Y,U).$$
(23)

The above expression (23) denotes the relation between $\widetilde{R}(X,Y)Z$ of M_n w.r.t. $\widetilde{\nabla}$ and R(X,Y)Z w.r.t. ∇ .

Put X = U = e_i in (23), where e_i be an orthonormal basis of the tangent space at any point of the manifold and taking summation over i (1 $\leq i \leq n$), we get

$$\widetilde{S}(Y,Z) = S(Y,Z) + n g(Y,Z) - \eta(Y)\eta(Z);$$
(24)

here \tilde{S} and S signifies the Ricci tensors of $\tilde{\nabla}$ and ∇ .

From (24), by using $Y = Z = e_i$, we obtain

$$\widetilde{r} = r + n^2 - 1; \tag{25}$$

here \tilde{r} and r indicates the scalar curvatures of $\tilde{\nabla}$ and ∇ correspondingly.

Theorem 3.1: Suppose that \tilde{S} be the Ricci tensor & \tilde{R} be the curvature tensor in an *SP*-Kenmotsu manifold M_n w.r.t. $\tilde{\nabla}$, then

- (a) $\widetilde{R}(X,Y)Z + \widetilde{R}(Y,Z)X + \widetilde{R}(Z,X)Y = 0$,
- (b) $\widetilde{R}(X,Y,Z,U) + \widetilde{R}(X,Y,U,Z) = 0$,
- (c) $\widetilde{R}(X,Y,Z,U) \widetilde{R}(Z,U,X,Y) = 0$,
- (d) $\widetilde{R}(X,Y,Z,\xi) = 2R(X,Y,Z,\xi),$

(e)
$$S(X,\xi) = 2S(X,\xi)$$
.

Proof: Using first Bianchi identity and eq.(22) w.r.t. the Riemannian connection, we obtain (*a*).

From eq. (23), we obtain (*b*) & (*c*). By putting $U = \xi$ in (23) and by using (8) we have (d).

By using $Y = Z = e_i$ in equation (d) as well as summation with i, we obtain (e).

Theorem 3.2: The Ricci tensor \tilde{S} in an *SP*-Kenmotsu manifold M_n w.r.t. the connection for the quarter-symmetric metric is symmetrical.

Proof: The theorem-proof is based on the eq. provided in (24).

IV. CONCIRCULAR CURVATURE TENSOR

The n-dimensional Riemannian manifold M_n is provided by the concircular curvature tensor Z(X, Y) [11, 13]:

$$Z(X,Y)U = R(X,Y)U - \frac{r}{n(n-1)}[g(Y,U)X - g(X,U)Y]$$
(26)

for all X, Y, $U \in TM$.

The concircular curvature tensor w.r.t. $\widetilde{\nabla}$ in an *SP*-Kenmotsu manifold is \widetilde{Z} .

Therefore, using the equations (22) and (26), we get

$$\widetilde{Z}(X,Y)U = Z(X,Y)U - \frac{1}{n}[g(Y,U)X - g(X,U)Y],$$
(27)

which denotes the relation between the concircular curvature tensors w.r.t. $\tilde{\nabla}$ and ∇ .

Theorem 4.1: If \tilde{Z} w.r.t. $\tilde{\nabla}$ in an *SP*-Kenmotsu manifold satisfies $\tilde{R}(\xi, U).\tilde{Z} = 0$, the manifold is η -Einstein.

Proof: Suppose $\widetilde{R}(\xi, U)$. $\widetilde{Z}(X, Y)\xi = 0$, in an *SP*-Kenmotsu manifold.

Then

$$(\widetilde{R}(\xi, U).\widetilde{Z}(X, Y)\xi) - \widetilde{Z}(\widetilde{R}(\xi, U)X, Y)\xi - \widetilde{Z}(X, \widetilde{R}(\xi, U)Y)\xi - \widetilde{Z}(X, Y).\widetilde{R}(\xi, U)\xi = 0.$$
(28)

Also, from (8) and (22), we get

$$\widetilde{R}(X,Y)\xi = 2[\eta(Y)X - \eta(X)Y] \text{ and}$$
(29)

$$\widetilde{R}(\xi, X)U = 2[g(X, U)\xi - \eta(U)X].$$
(30)

Then, by using (28), (29) and (30), we get

$$\widetilde{Z}(X,Y)U = 0. \tag{31}$$

Now, using the equations (26) and (27), the equation (31) reduces to

$$\mathbb{R}(X,Y,U) = \frac{r+n-1}{n(n-1)} [g(Y,U)X - g(X,U)Y].$$
(32)

We obtain with the above equation w.r.t. X,

$$S(Y,U) = \frac{r+n-1}{n(n-1)} [ng(Y,U)X - \eta(Y)\eta(U)],$$
(33)

which on further contracting, we get

$$r = 1 - n^2.$$
 (34)

Using (34), the expression (33) becomes

$$S(Y,U) = \eta(Y)\eta(U) - ng(Y,U);$$
(35)

which proves η -Einstein manifold.

Theorem 4.2: If \tilde{Z} with respect to $\tilde{\nabla}$ in an *SP*-Kenmotsu manifold satisfies $\tilde{Z}(\xi, U).\tilde{R} = 0$, the manifold is an η -Einstein.

Proof: Suppose that $\widetilde{Z}(\xi, U) \cdot \widetilde{R}(X, Y) \xi = 0$, in an *SP*-Kenmotsu manifold.

Then

$$(\widetilde{Z}(\xi, U).\widetilde{R}(X, Y)\xi) - \widetilde{R}(\widetilde{Z}(\xi, U)X, Y)\xi - \widetilde{R}(X, \widetilde{Z}(\xi, U)Y)\xi - \widetilde{R}(X, Y).\widetilde{Z}(\xi, U)\xi = 0$$
(36)

Also, from (8), (26) and (27), we have

$$\widetilde{Z}(\xi, U)Y = \left[\frac{r}{n(n-1)} + \frac{1}{n} - 1\right] \left[g(U, Y)\xi - \eta(Y)U\right]$$
(37)

and

$$\widetilde{Z}(X,Y)\xi = \left[\frac{r}{n(n-1)} + \frac{1}{n} - 1\right] \left[\eta(X)Y - \eta(Y)X\right].$$
(38)

By substituting the values from (29), (30), (37) and (38) in the expression (36), we obtain

$$\widetilde{R}(X,Y)U = g(U,Y)X - g(U,X)Y + \eta(U)[1 - \eta(X)]Y.$$
(39)

Using (22), the above eq. becomes

$$R(X,Y)U = \eta(U)[1 - \eta(X)]Y;$$
(40)

and it proves.

Theorem 4.3: If the \tilde{Z} w.r.t. $\tilde{\nabla}$ in an *SP*-Kenmotsu manifold meets $\tilde{Z}(\xi, U).\tilde{Z} = 0$, the manifold is η -Einstein.

Proof: The theorem-proof is trivial by the use of the fact that $\widetilde{Z}(\xi, U).\widetilde{Z}$ indicates $\widetilde{Z}(\xi, U)$ was acting on \widetilde{Z} as a derivation.

Theorem 4.4: If \widetilde{Z} (concircular curvature tensor) with respect to $\widetilde{\nabla}$ (quarter symmetric metric connection) in an *SP*-Kenmotsu manifold fulfills $\widetilde{Z}(X, Y).\widetilde{S} = 0$, the manifold signifies η -Einstein.

Proof: Let $\widetilde{Z}(X, Y)$. $\widetilde{S}(U, V) = 0$ in an *SP*-Kenmotsu manifold.

Then it means

$$\widetilde{S}(\widetilde{Z}(X,Y)U,V) + \widetilde{S}(U,\widetilde{Z}(X,Y)V) = 0.$$
(41)

By choosing $X = \xi$ in (41) and on using the equations (37) and (24), we obtain

$$\left[\frac{r}{n(n-1)} + \frac{1}{n} - 1\right] \left[-\eta(U)S(Y, V) - n\eta(U)g(Y, V) + 2\eta(U)\eta(V)\eta(Y) - \eta(V)S(U, Y) - n\eta(V)g(U, Y)\right] = 0.$$
(42)

Again by using $U = \xi$ in the eq. (42), we get

$$S(Y,V) = \eta(Y)\eta(V) - ng(Y,V);$$
(43)

which provides the required result.

V. Conformal curvature tensor

The Weyl conformal curvature tensor *C* of the type (0, 4) of a manifold M_n w.r.t. a Riemannian connection provided by [12, 13]:

$$C(X,Y,Z,U) = R(X,Y,Z,U) - \frac{1}{n-2} [S(Y,Z)g(X,U) - S(X,Z)g(Y,U) + g(Y,Z)S(X,U) - g(X,Z)S(Y,U)] + \frac{r}{(n-1)(n-2)} [g(Y,Z)g(X,U) - g(X,Z)g(Y,U)].$$
(44)

Analogous to this, we define \tilde{C} i.e.Weyl conformal curvature tensor of the type (0,4), of an *SP*-Kenmotsu manifold w.r.t. the quarter-symmetric metric connection as:

$$\widetilde{C}(X,Y,Z,U) = \widetilde{R}(X,Y,Z,U) - \frac{1}{n-2} [\widetilde{S}(Y,Z)g(X,U) - \widetilde{S}(X,Z)g(Y,U) + g(Y,Z)\widetilde{S}(X,U) - g(X,Z)\widetilde{S}(Y,U)] + \frac{\widetilde{r}}{(n-1)(n-2)} [g(Y,Z)g(X,U) - g(X,Z)g(Y,U)].$$

$$(45)$$

Then, using the equations (23), (24), (25), (44) and (45), we get

$$\widetilde{C}(X,Y,Z,U) = C(X,Y,Z,U),$$
(46)

which implies the following statement:

Theorem 5.1: The conformal curvature tensors of $\widetilde{\nabla}$ and ∇ are equal in an *SP*-Kenmotsu manifold.

Suppose that
$$\widetilde{R} = 0$$
. Then $\widetilde{S} = 0$ and $\widetilde{r} = 0$.

From (45) we get that $\tilde{C} = 0$ and hence using (46), we get C = 0.

Therefore, we provide the following theorem.

Theorem 5.2: The manifold is conformally flat in an *SP*-Kenmotsu manifold if the conformal curvature tensor \widetilde{C} of $\widetilde{\nabla}$ vanishes.

Let $\tilde{S} = 0$. Then $\tilde{r} = 0$. Hence from (24) and (25), we get

$$S(Y,Z) = \eta(Y)\eta(Z) - n g(Y,Z)$$
(47)

and

$$r = 1 - n^2$$
. (48)

Then by using (23), (44), (47) and (48), we obtain

$$\widehat{R}(X,Y,Z,U) = C(X,Y,Z,U).$$
⁽⁴⁹⁾

From (49), we state that

Theorem 5.3: Conformal curvature tensor *C* of the manifold is identical in an *SP*-Kenmotsu manifold if \tilde{S} (Ricci tensor) of $\tilde{\nabla}$ i.e quarter-symmetric metric connection vanishes, then \tilde{R} i.e. curvature tensor of $\tilde{\nabla}$.

Using theorem (5.2) and (5.3), we state that

Theorem 5.4: If \tilde{S} of $\tilde{\nabla}$ in an *SP*-Kenmotsu manifold disappears, then the manifold is conformally flat if \tilde{R} of $\tilde{\nabla}$ vanishes.

VI. Example of a 3d SP-Kenmotsu manifold admitting the quarter-symmetric metric connection

Example 6.1: Suppose that 3d manifold $M = \{(x, y, u) \in \mathbb{R}^3\}$, where (x, y, u) indicates "standard coordinates" in \mathbb{R}^3 . Considering $e_1, e_2 \& e_3$ be fields of vector in M as

$$e_1 = e^{-u} \frac{\partial}{\partial x}, \quad e_2 = e^{-u} \frac{\partial}{\partial y}, \quad e_3 = \frac{\partial}{\partial u}.$$
 (50)

for each point of M are linearly independent vectors and constitute a basis of $\chi(M)$.

Riemannian metric g(X, Y) is

$$g(e_i, e_j) = \begin{cases} 1, & if \ i = j \\ 0, & if \ i \neq j; i, j = 1, 2, 3, 4, 5. \end{cases}$$

 $Let\eta(Z) = g(Z, e_3), for any Z \in \chi(M)$

Let η be a 1-form & (1, 1)-tensor field on M expressed by Φ defined as

$$\Phi^2(e_1) = e_1, \Phi^2(e_2) = e_2, \Phi^2(e_3) = 0.$$

The g(X, Y) and linearity of Φ yields that

$$\eta(e_3) = 1, \ \Phi^2(X) = X - \eta(X)e_3$$
; and
 $g(\Phi X, \Phi Y) = g(X, Y) - \eta(X)\eta(Y)$

for all vector fields *X*, $Y \in \chi(M)$.

Thus for $e_3 = \xi$, (Φ, ξ, η, g) describes an almost para-contact structure in M.

Let ∇ be a Riemannian connection in regard to the Riemannian metric *g*.

$$[e_1, e_2] = 0, [e_1, e_3] = e_1, [e_2, e_3] = e_2.$$

The formula of Koszul's is

$$2g(\nabla_X Y, Z) = Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) - g(X, [Y, Z]) - g(Y, [X, Z]) + g(Z, [X, Y]).$$
(51)

By taking $e_3 = \xi$ in (51), one can get

$$\begin{aligned} \nabla_{e_1} e_1 &= -e_3, \nabla_{e_1} e_2 = 0, \nabla_{e_1} e_3 = e_1; \\ \nabla_{e_2} e_1 &= 0, \nabla_{e_2} e_2 = -e_3, \nabla_{e_2} e_3 = e_2; \\ \nabla_{e_3} e_1 &= 0, \nabla_{e_3} e_2 = 0, \nabla_{e_3} e_3 = 0. \end{aligned}$$

Therefore manifold under consideration satisfies $\nabla_X \xi = \Phi^2 X = X - \eta(X)\xi$, $\eta(\xi) = 1$ and the expression (3)d.

The above expressions satisfy all the properties of *SP*-Kenmotsu manifold with (Φ, ξ, η, g) . Thus $M(\Phi, \xi, \eta, g)$ is a 3-dimensional manifold.

Further from (20), we get

$$\begin{split} \widetilde{\nabla}_{e_{1}}e_{1} &= -2e_{3}, \widetilde{\nabla}_{e_{1}}e_{2} = 0, \widetilde{\nabla}_{e_{1}}e_{3} = 2e_{1}; \\ \widetilde{\nabla}_{e_{2}}e_{1} &= 0, \widetilde{\nabla}_{e_{2}}e_{2} = -2e_{3}, \widetilde{\nabla}_{e_{2}}e_{3} = 2e_{2}; \\ \widetilde{\nabla}_{e_{3}}e_{1} &= 0, \widetilde{\nabla}_{e_{3}}e_{2} = 0, \widetilde{\nabla}_{e_{3}}e_{3} = 0; \end{split}$$

Therefore T(X, Y) of $\widetilde{\nabla}$ can be expressed as:

$$T(e_i, e_i) = 0$$
, for $i = 1, 2, 3$; and
 $T(e_1, e_2) = 0$, $T(e_1, e_3) = e_1$, $T(e_2, e_3) = e_2$.

Also, we get

$$(\widetilde{\nabla}_{e_1}g)(e_2,e_3) = 0, (\widetilde{\nabla}_{e_2}g)(e_3,e_1) = 0, (\widetilde{\nabla}_{e_3}g)(e_1,e_2) = 0,$$

which proves that the manifold *M* under consideration admits $\widetilde{\nabla}$.

Thus it proves that *M* under consideration is an *SP*-Kenmotsu manifold and allows $\widetilde{\nabla}$.

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